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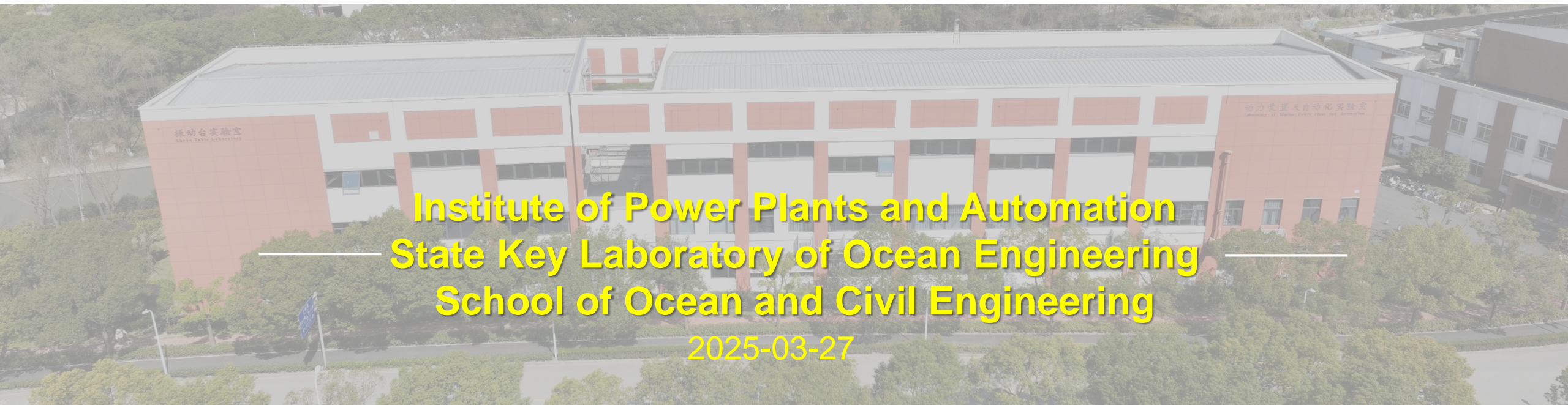


大发动机研究中心
LARGE ENGINE RESEARCH CENTER

*Singapore Maritime Research Conference
(SMRC) 2025*

A Six-Dimension Framework for Digital Twin of Marine Engine Systems

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School of Ocean and Civil Engineering

2025-03-27



What is digital twin (DT)?

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Digital Twins are virtual replicas of a physical devices, systems or processes, that are used to leverage real-time data, advanced analytics and machine learning to create dynamic models to mirrors its real-world counterpart in real-time.

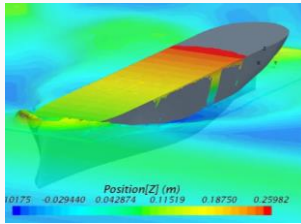
WHAT IS
DIGITAL
TWIN?



Computer Aided Engineering



CAE



CAD

Tools of DT

- **Purpose:** analysis, prediction, understanding, etc.
- **Scope:** specific scenarios, research & design, etc.
- **Data integration:** off-line, predefined inputs
- **Static:** snapshot of objects for specific conditions



Digital Twins



- **Purpose:** optimization, predictive maintenance, etc.
- **Scope:** entire lifecycle, real-time interactions
- **Data integration:** real time, ML-/physical-models
- **Dynamic:** continuously updating real-world data



PLM

PRODUCT LIFECYCLE
MANAGEMENT

The concept of digital twin was first
proposed - Product Lifecycle
Management (PLM) ²
(University of Michigan)

2003



'Digital Twin' is officially
named ⁴
(NASA)
2010



Digital twin has
become a key research
point in industries ⁴

2012-

Year

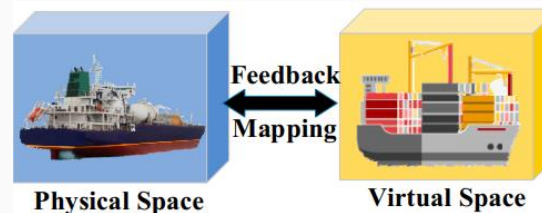
1970

NASA used a virtual model
to help restore Apollo 13 ¹



2005

Mirrored Spaces Model
was proposed ³



2011

Digital twin was applied for Air
Force aircraft health management ⁵



1. [Apollo 13: The First Digital Twin | Simcenter \(siemens.com\)](#)

2. Grieves M. Digital twin : manufacturing excellence through virtual factory replication. White paper; 2014.

3. Grieves MW. Product lifecycle management: the new paradigm for enterprises. Int J Prod Dev 2005;2(1-2):71-84.

4. Chinese digital twin white paper, 2020

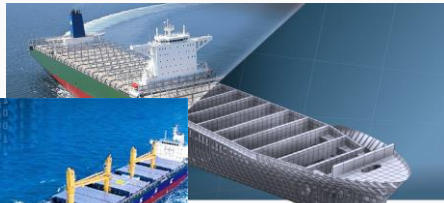
5. Tuegel EJ, Ingrassia AR, Eason TG, Spottswood SM. Reengineering aircraft structural life prediction using a digital twin. International Journal of Aerospace Engineering 2011.



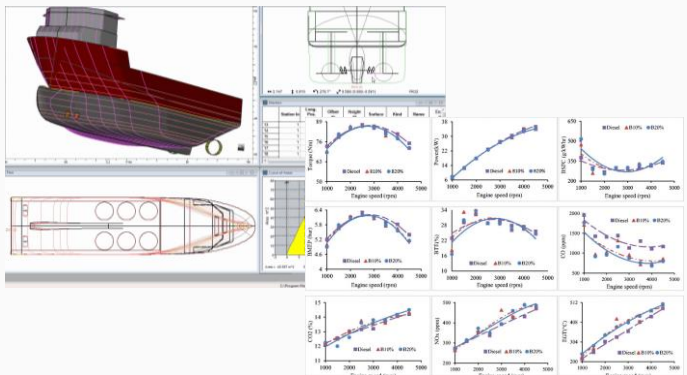
Benefits of digital twin in maritime industries



MBSE Aided ship design in early stage w/ LCA

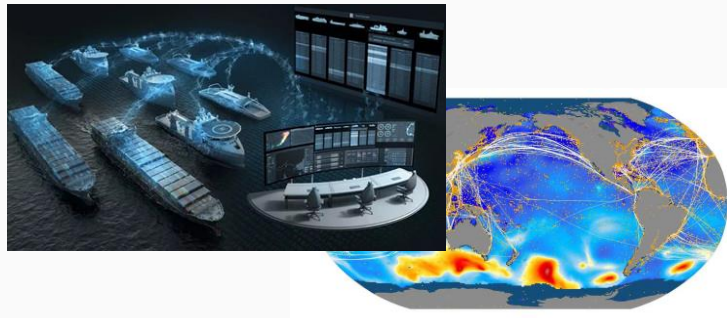


Real-time monitoring & predictive FMECA



Digital Twin

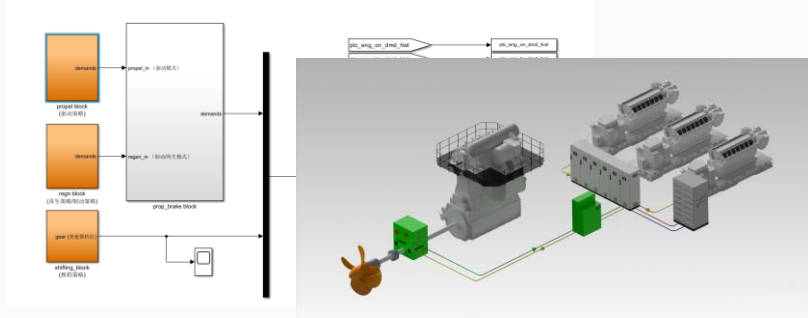
Predictive maintenance during ship operation



Mariners training in the digital world



Model-based control and energy flow management



Support classification for new marine technologies

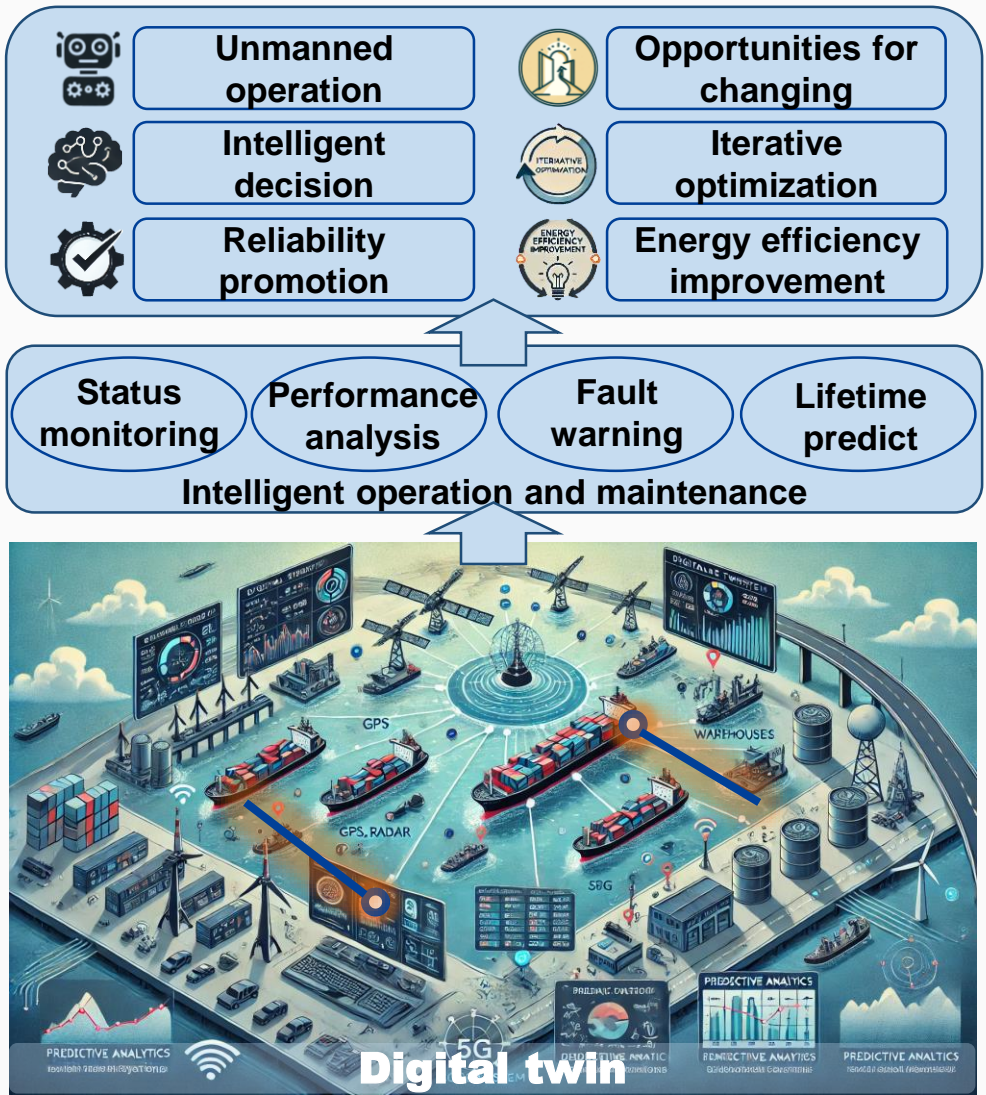
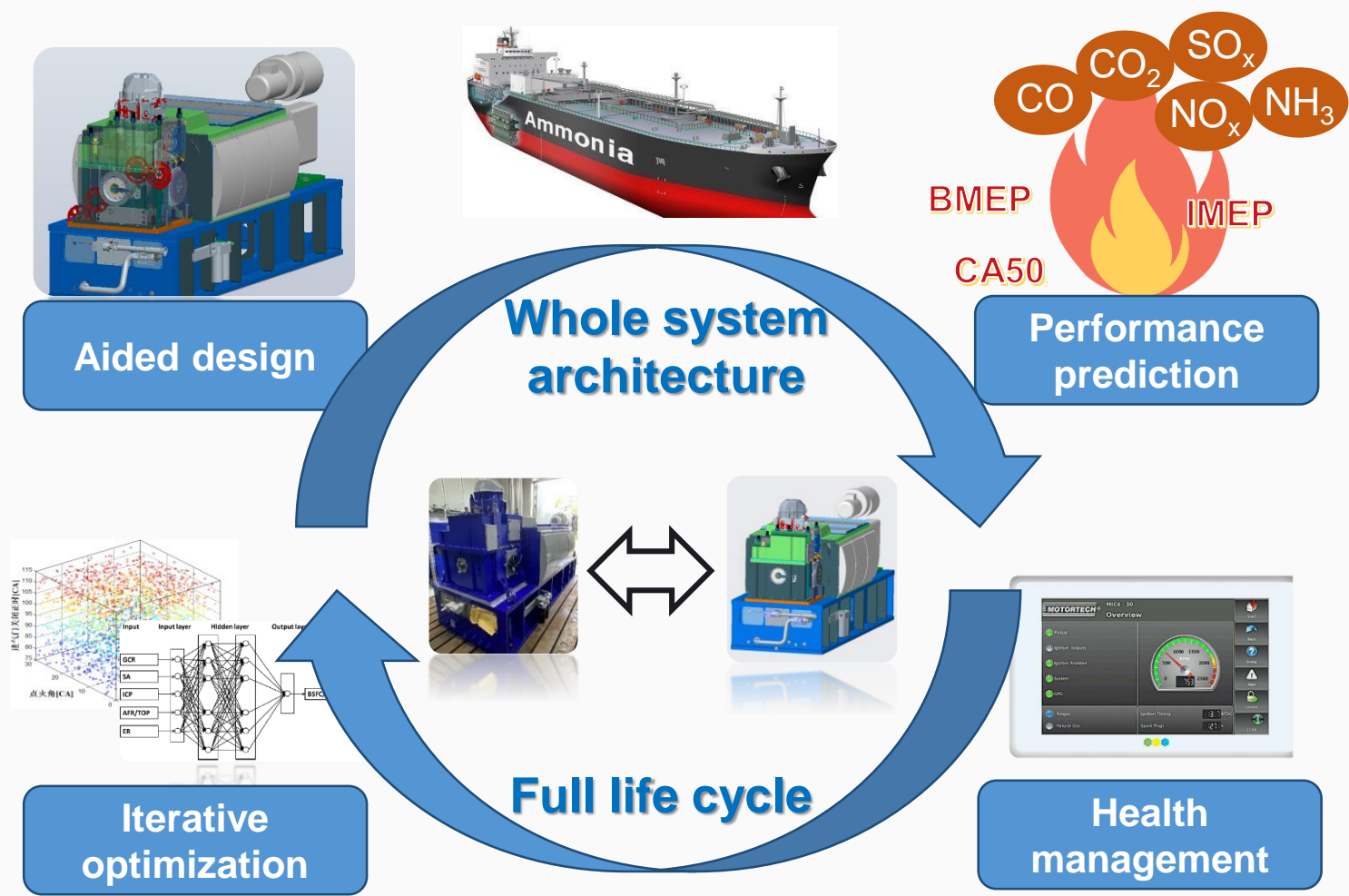




Benefits of digital twin for zero-carbon ships



Function of digital twin for marine engine system

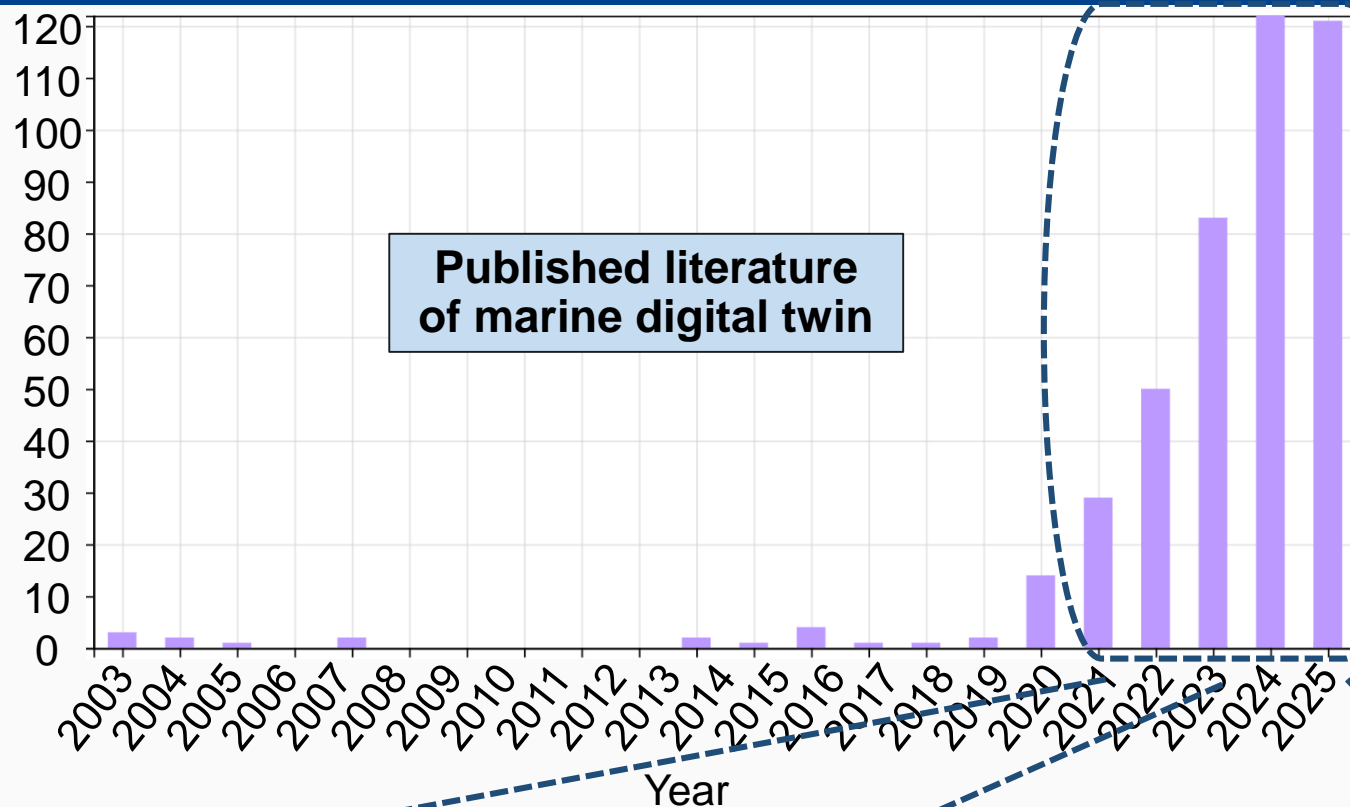


Digital twin is one of key technologies to realize the intelligent, digital, and green marine engine systems.



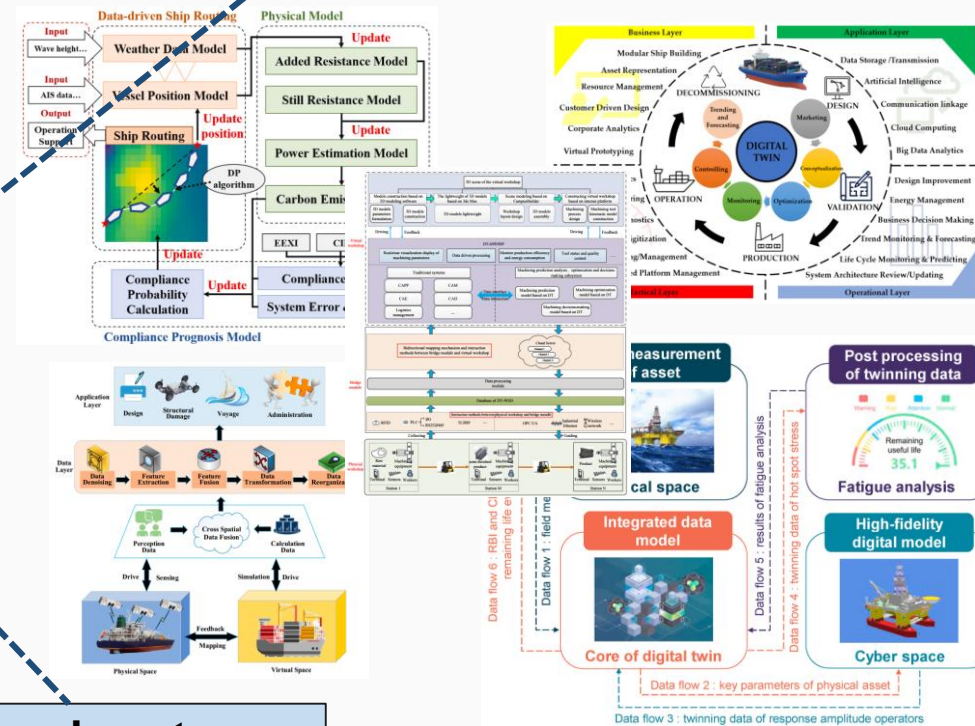
Progress in DT researches for marine engines⁶

Paper number

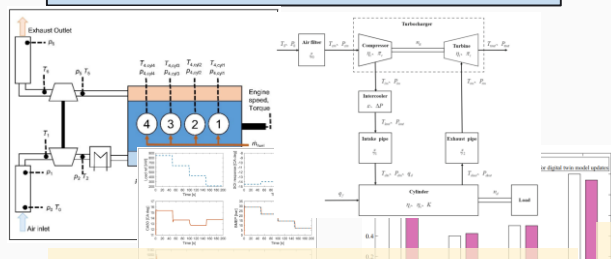


Published literature of marine digital twin

Framework



Real-time model



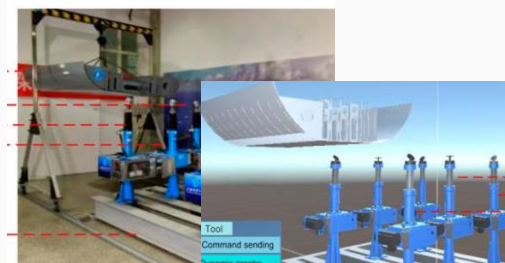
Fundamental of digital twin prediction function

Semi-physical bench



Lack of information interaction with real product and prediction model

3D visual system

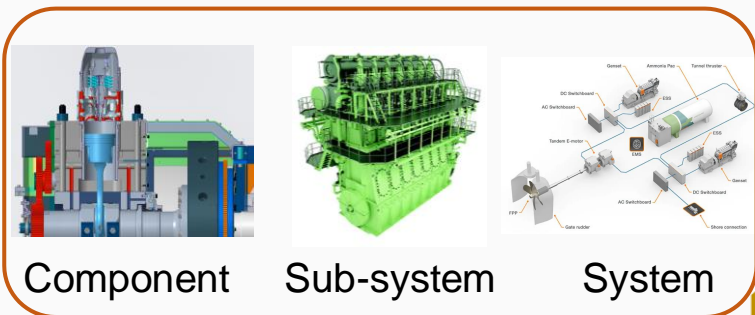


Lack of prediction model

GAP: There is still a big gap in the application of digital twin, especially for the complex equipment of the marine system

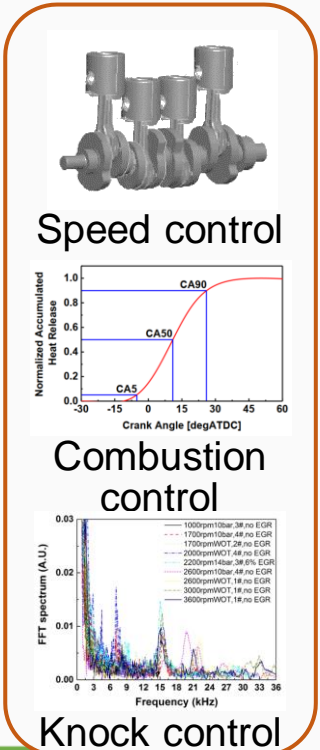


Challenges in building DT for marine engines



Complex structure

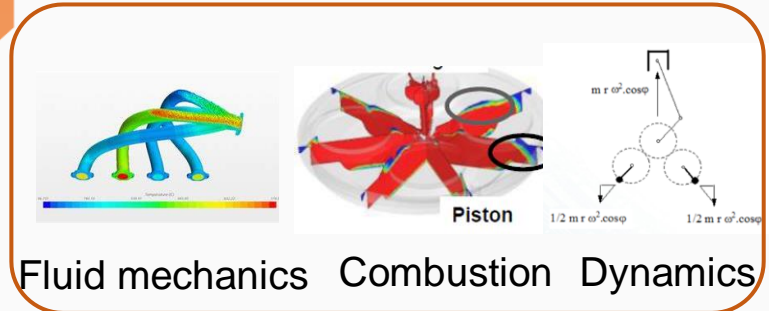
Real-time



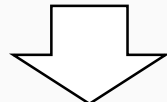
Challenges of engine system

Multi-scale

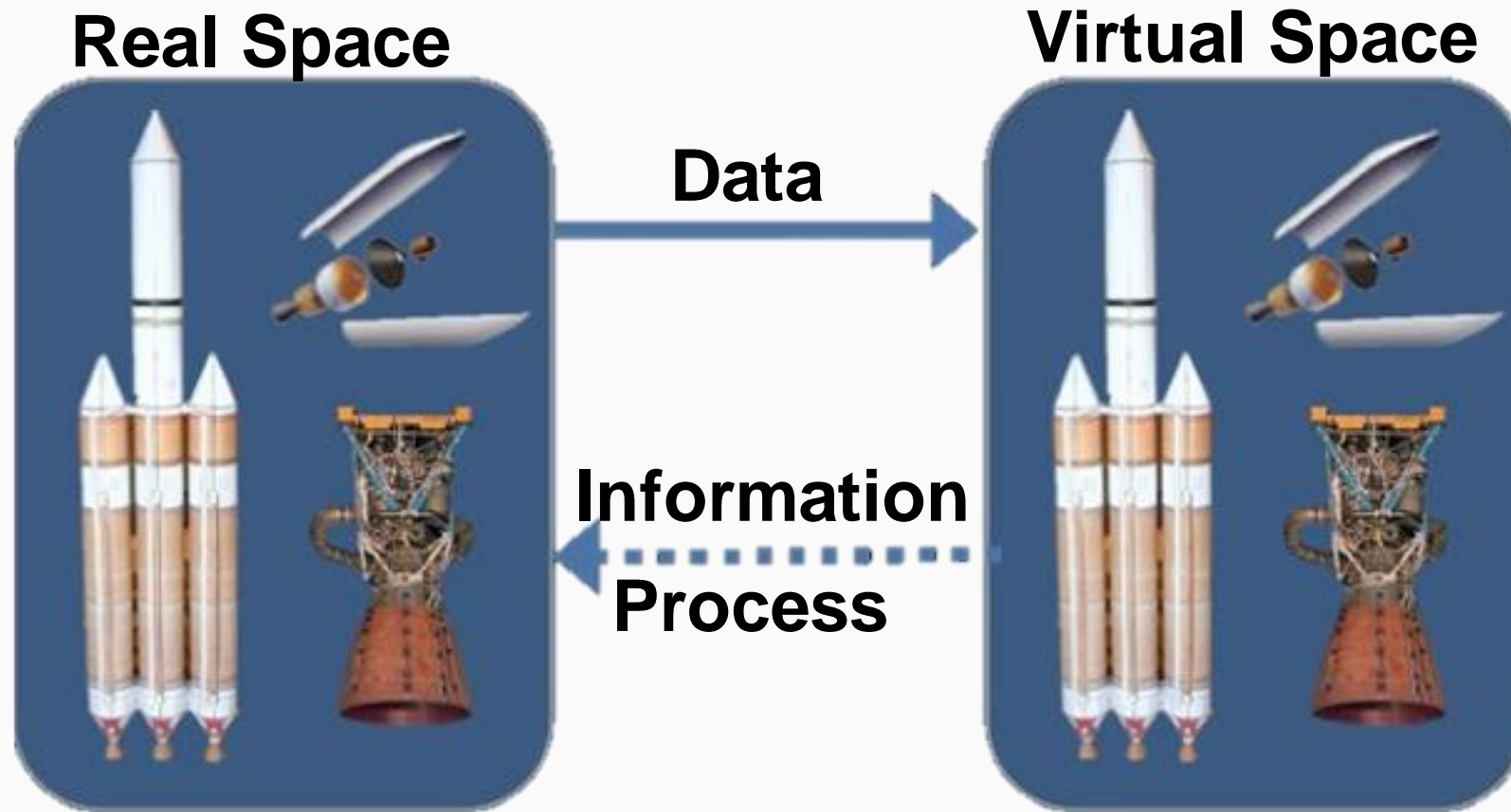
Multi-disciplinary



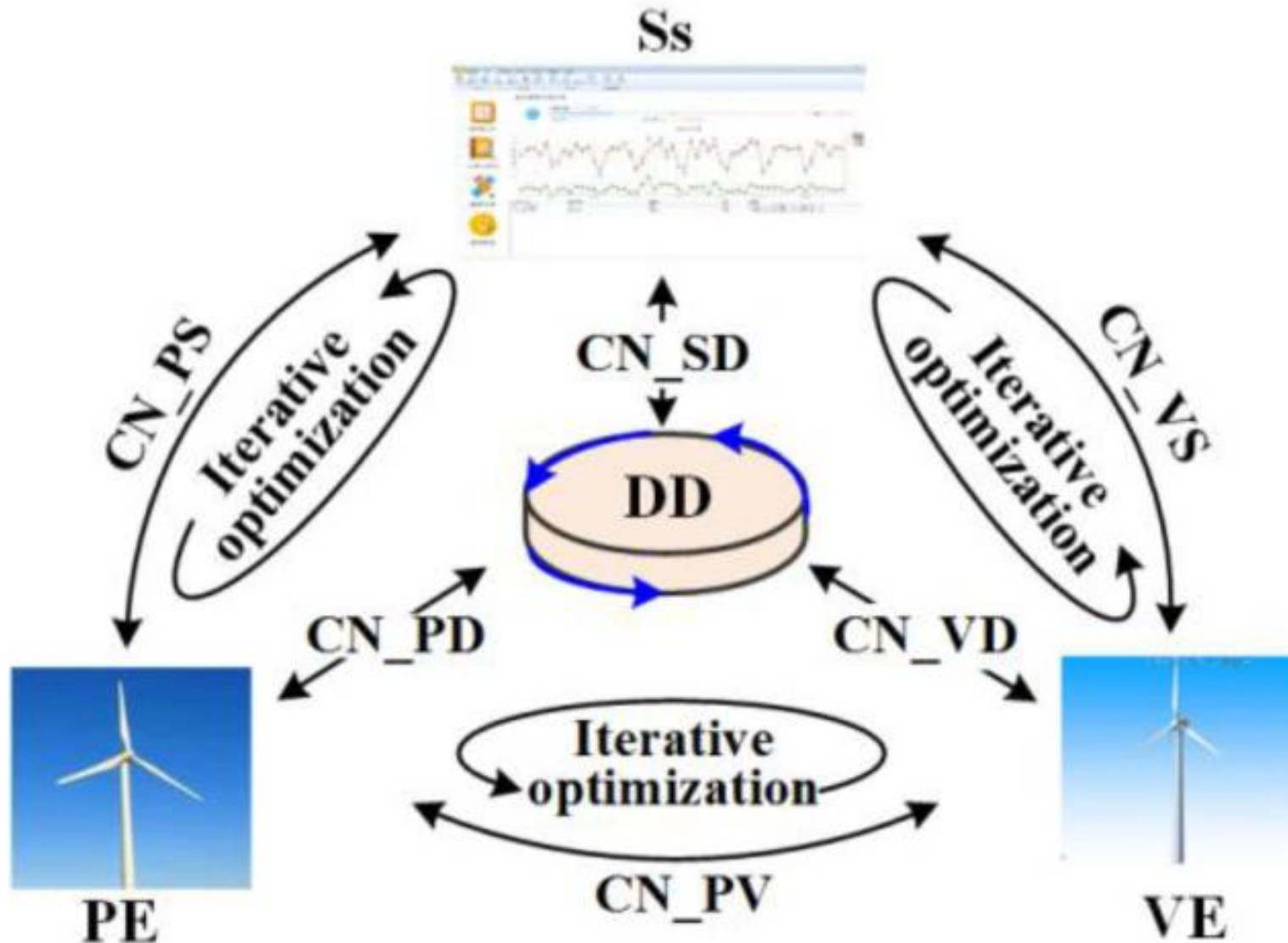
Challenges of digital twin models for marine system
Fidelity
Predictive
Real time
Reusability
Portability
Maintainability



How to construct **high-fidelity** **real-time** **quasi-predictive** twin model of marine system?



- Real Space
- Virtual Space
- Connects between the real and virtual space

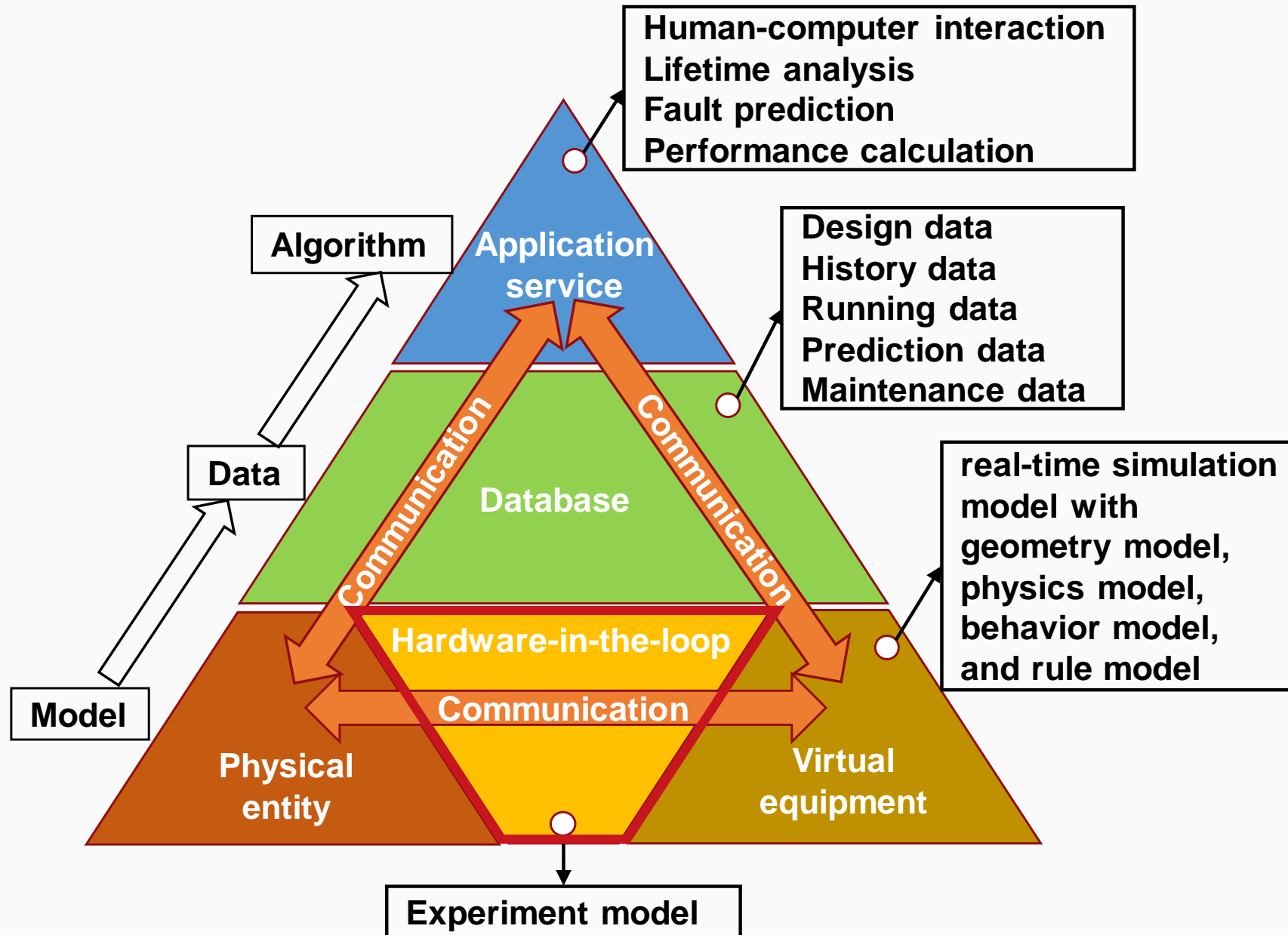


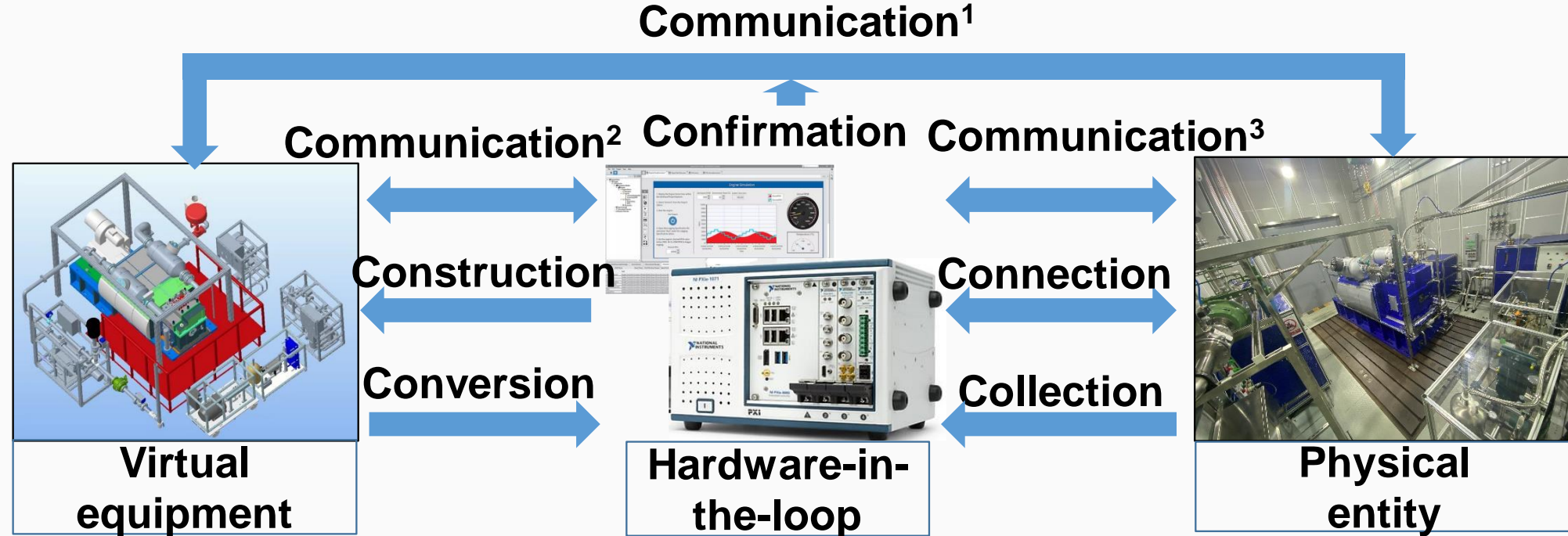
PE: Physical entity
VE: Virtual equipment
DD: Digital twin data
Ss: Services
CN: Connection



Six-dimension digital twin framework

10

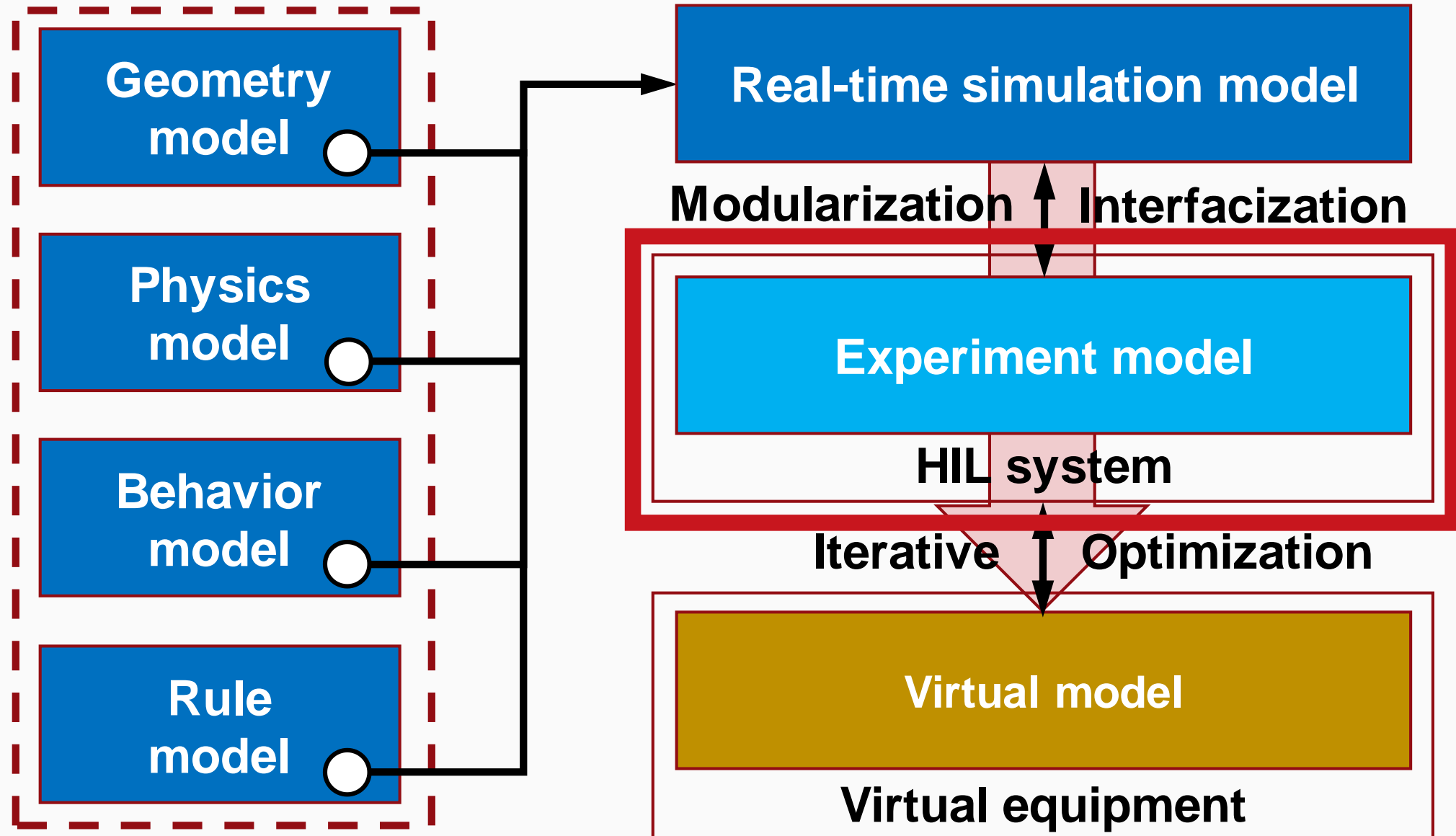


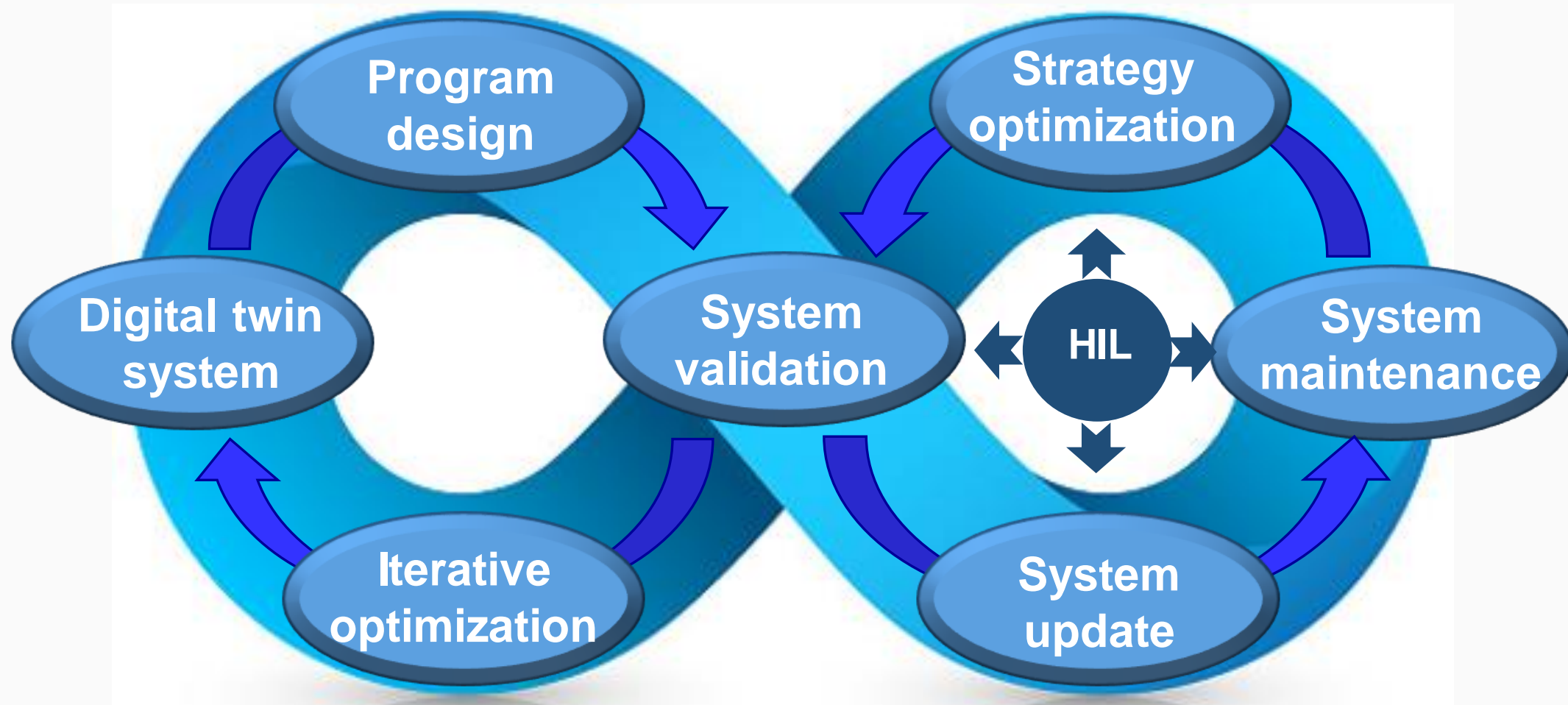


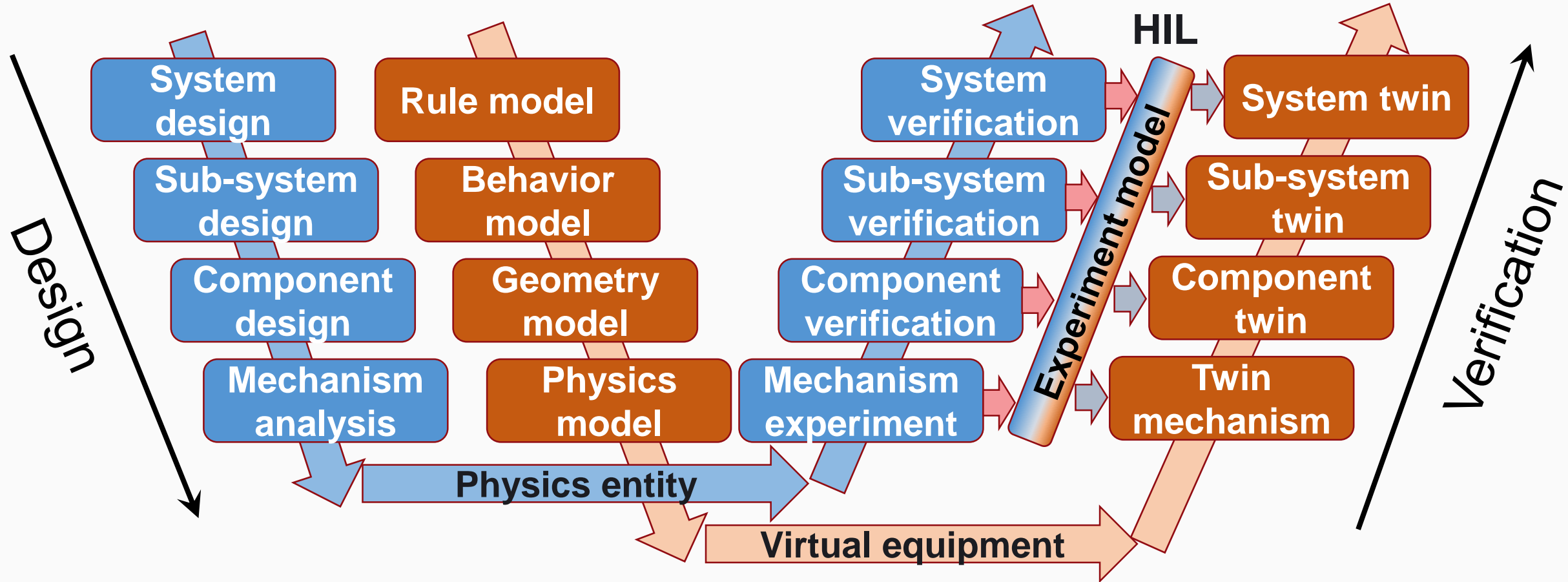
Communication:

1. Real-time signal, optimized control parameter to physical entity
2. Optimized model parameter to virtual equipment, real-time signal for HIL in validation of control strategies
3. Real-time signal

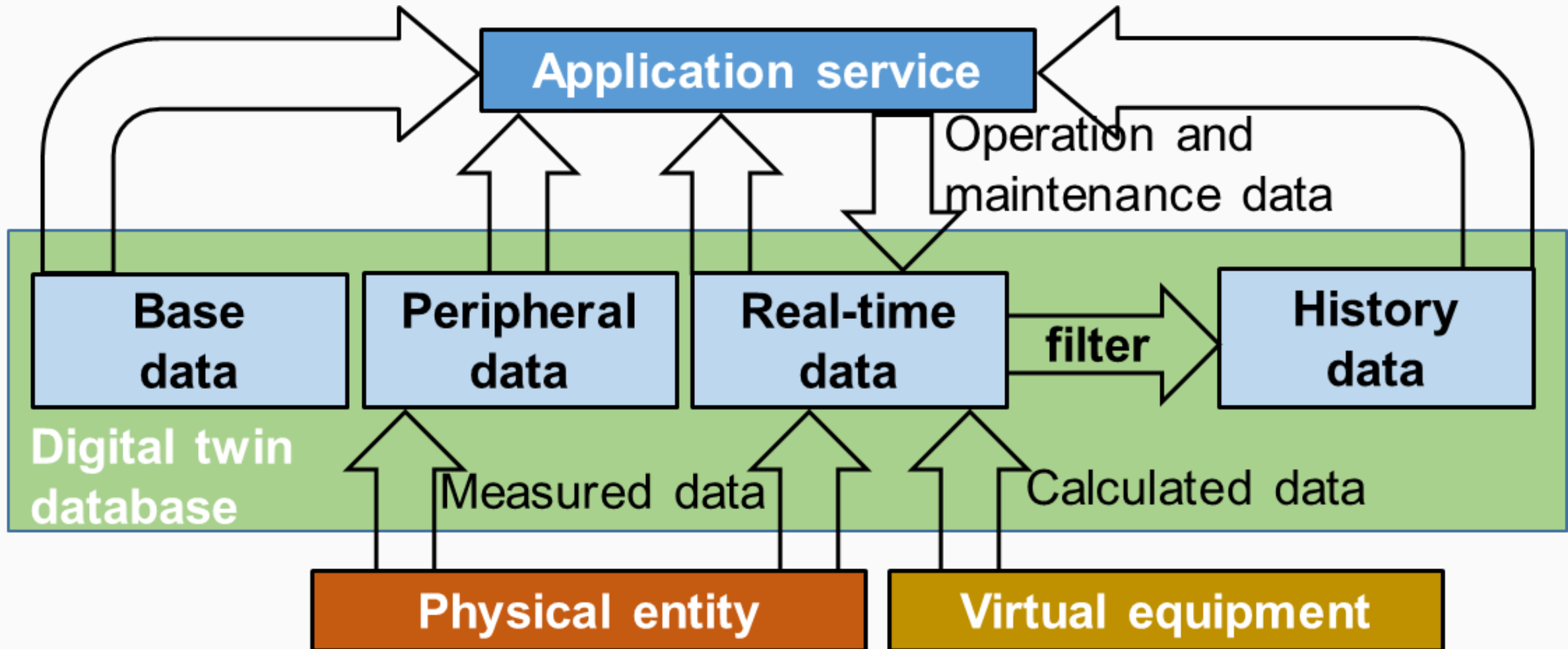
6C: Communication, Connection, Collection, Construction, Conversion, Confirmation

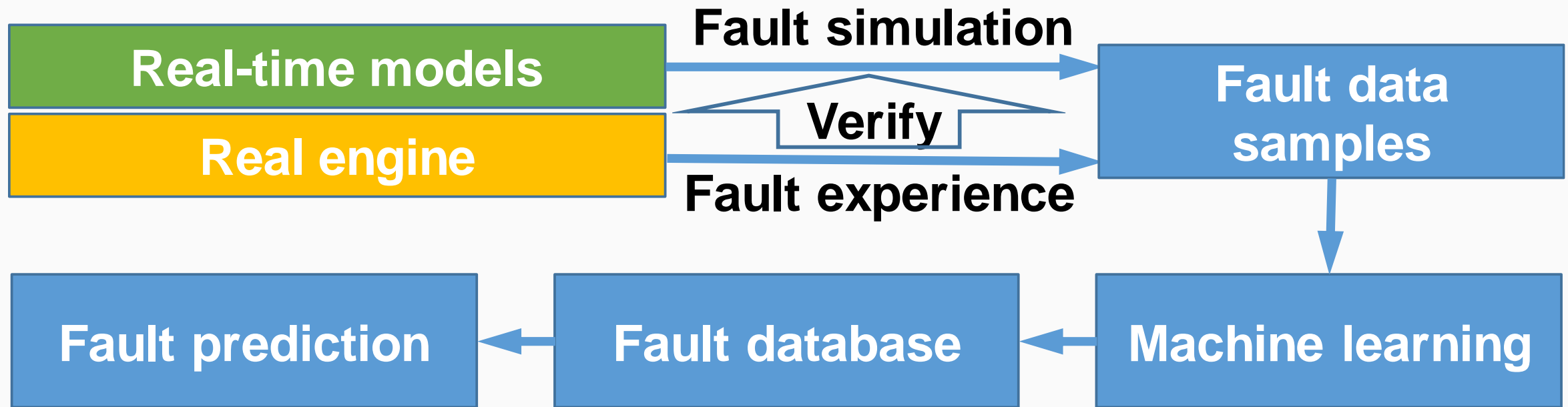




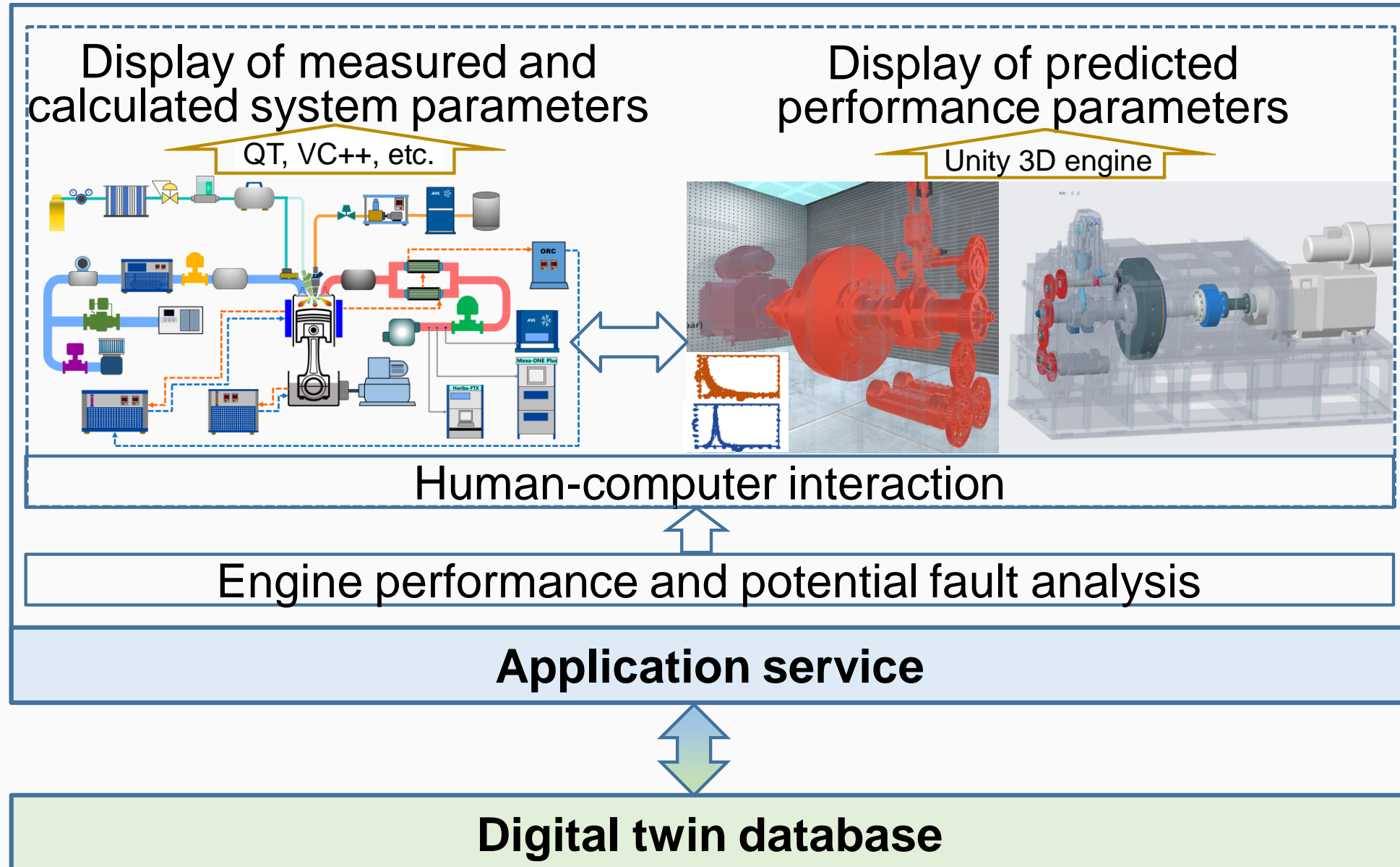


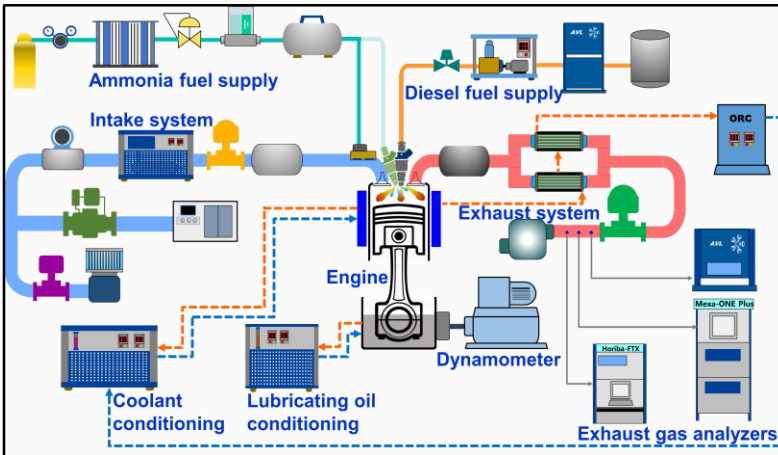
Double V-shaped digital twin modeling method



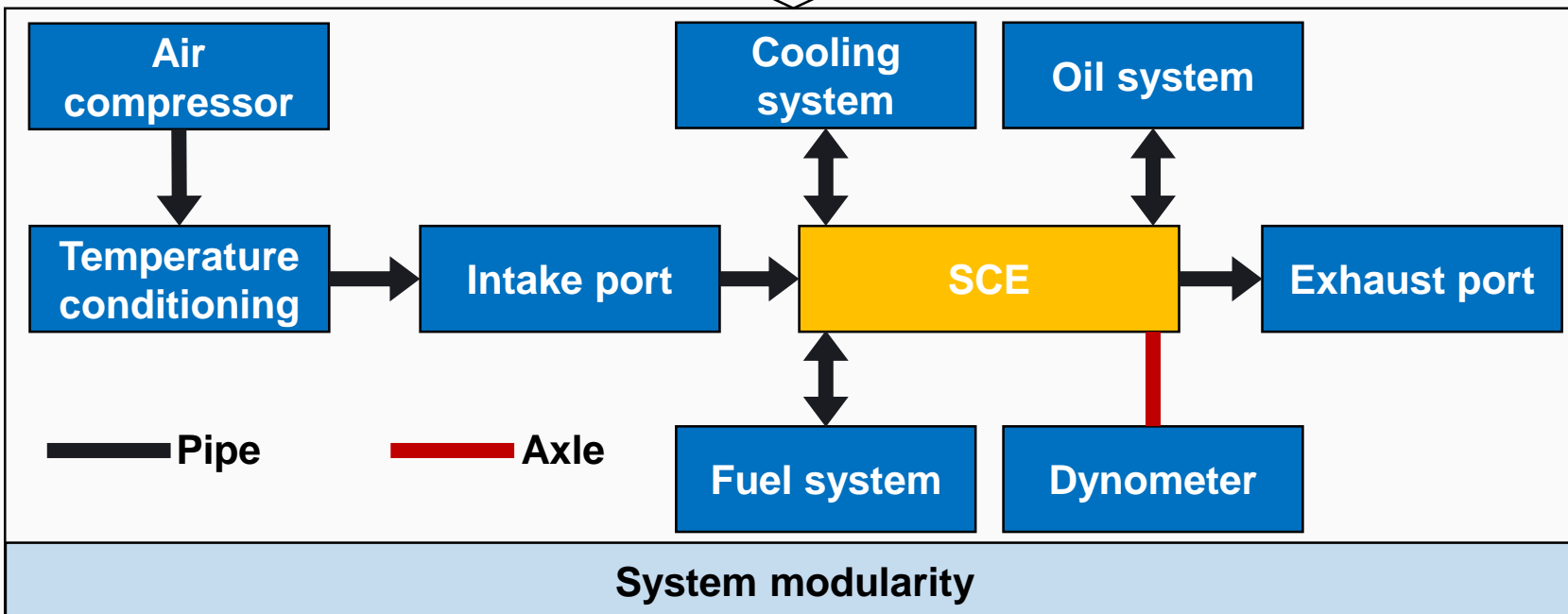


Fault prediction method based on digital twin





Specification	
Fuel	Flexible
Bore (mm)	175
Stroke (mm)	195
Comp. R(-)	15.6
Power (kW)	365
Speed (rpm)	2100
Max. IMEP(bar)	46.9



- Diesel / NG / Methanol / Ammonia / Hydrogen
- Simulated Turbocharging
- Regular / irregular exhaust emission measurement
- In-house R&D ECU
- Full instruments incl. pressure, temperature, vibration sensors



Development environment

Unity

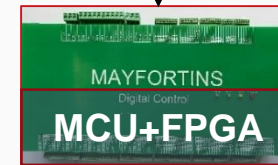
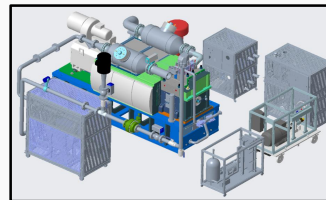
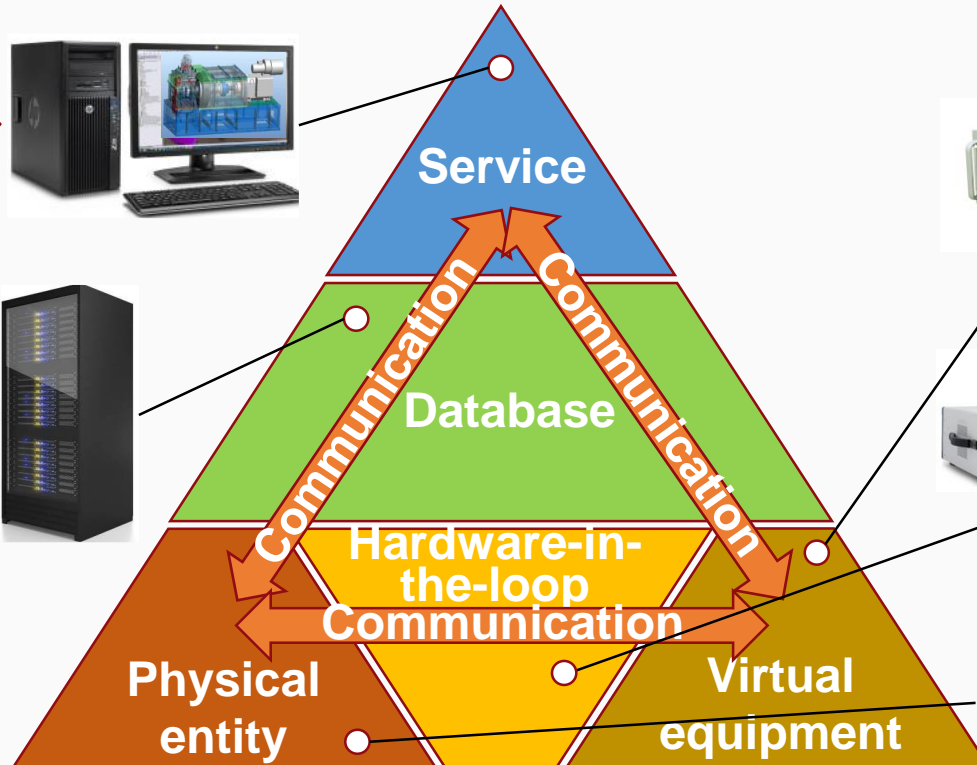
Qt Creator

Development Framework

spring boot

influxdb

Database



Development environment

Qt Creator

LabVIEW

LabVIEW

C Programming

Verilog

Transformer

Modeler

MATLAB SIMULINK

MATLAB SIMULINK

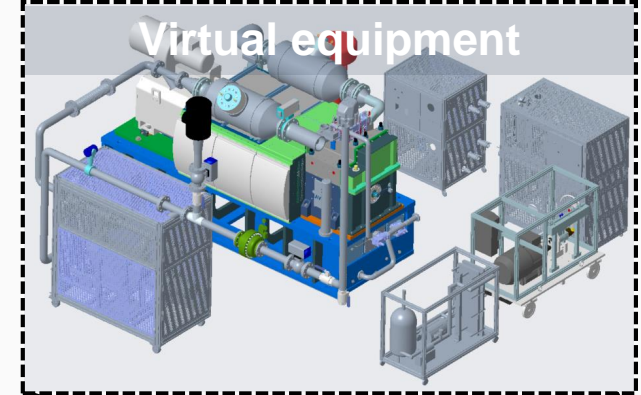
MATLAB SIMULINK



Physical entity



Control system



Virtual equipment



HIL system



Control system



Industrial computer
(Local twin)



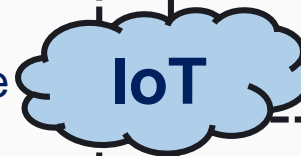
5G module

Engine room



Digital twin
client

Digital twin room



IoT



Data sever

Data center room

IoT : Internet of Things

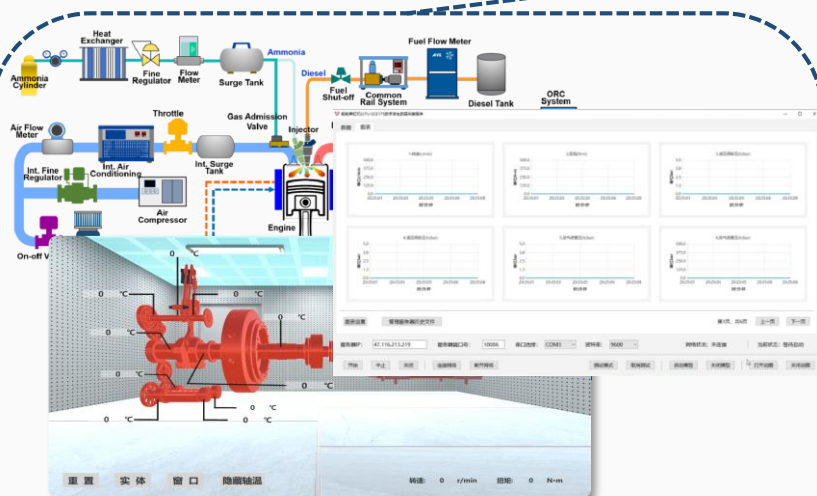
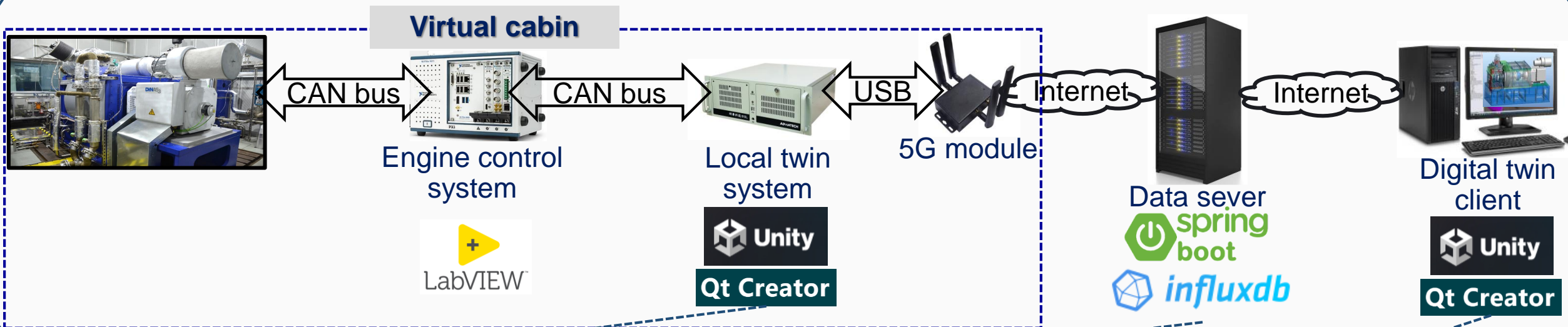


Digital twin of SJTU SCE175 engine system

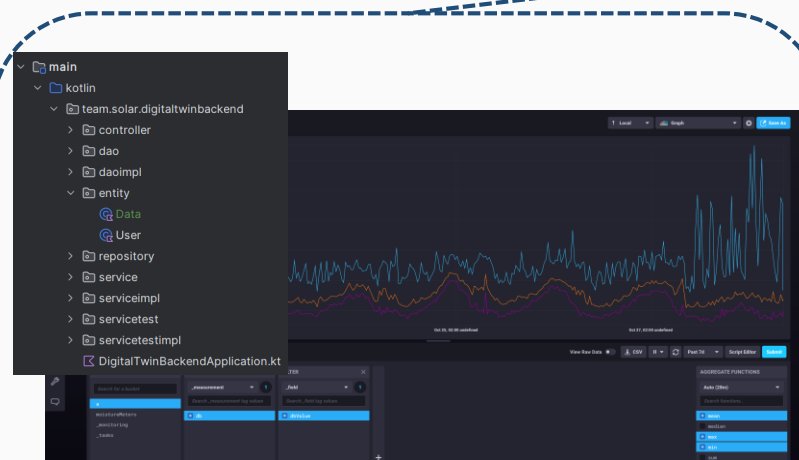
21



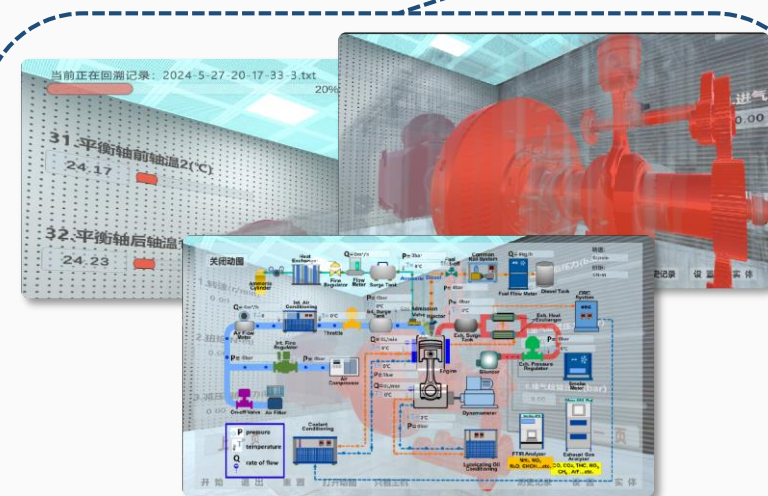
Communication Frame



Local twin system



Data sever

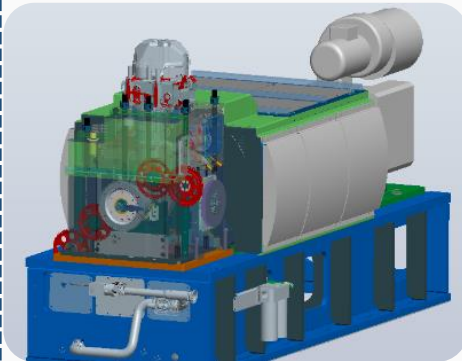


Digital twin client

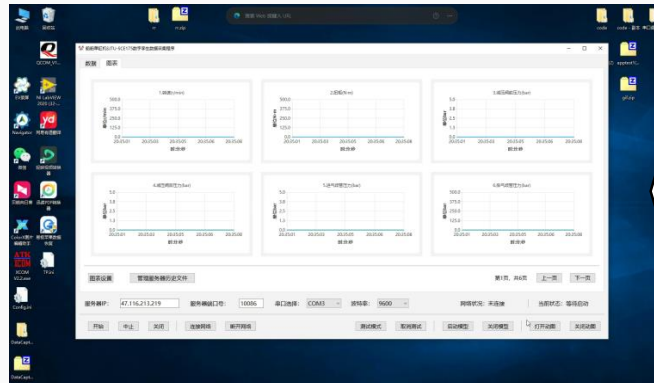
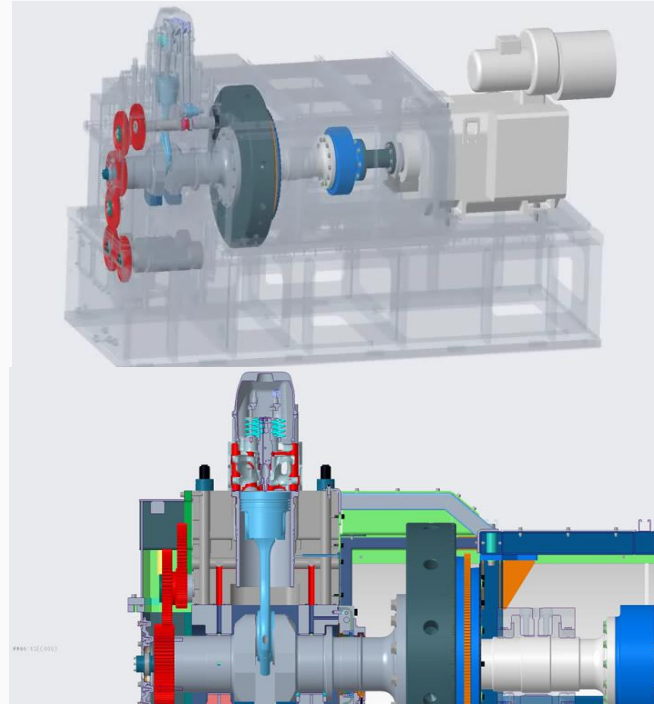
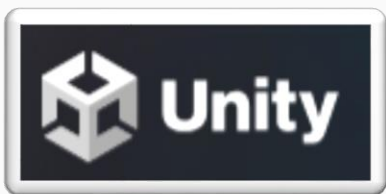


Digital twin of SJTU SCE175 engine system

22

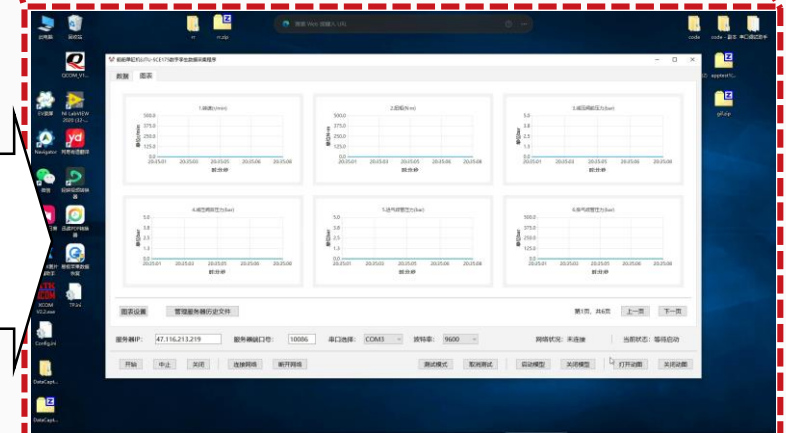
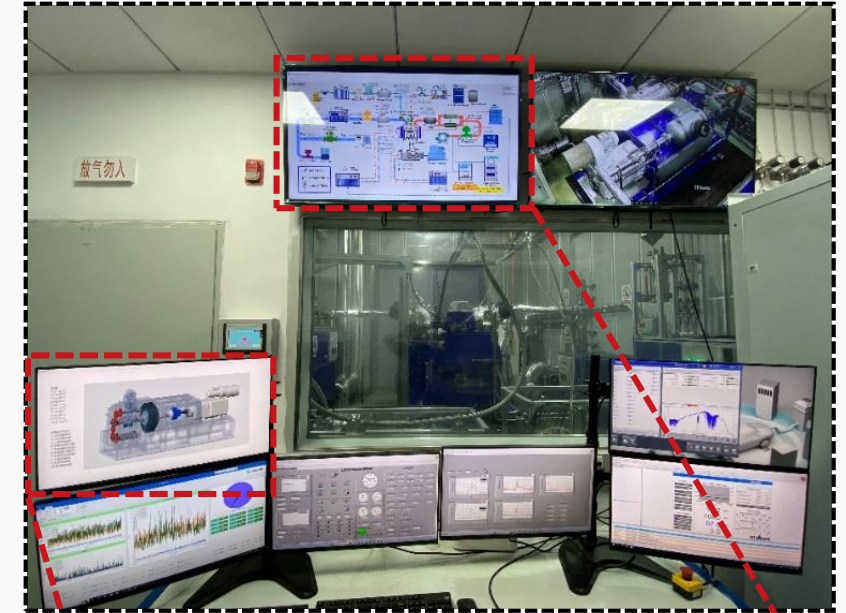


3D model



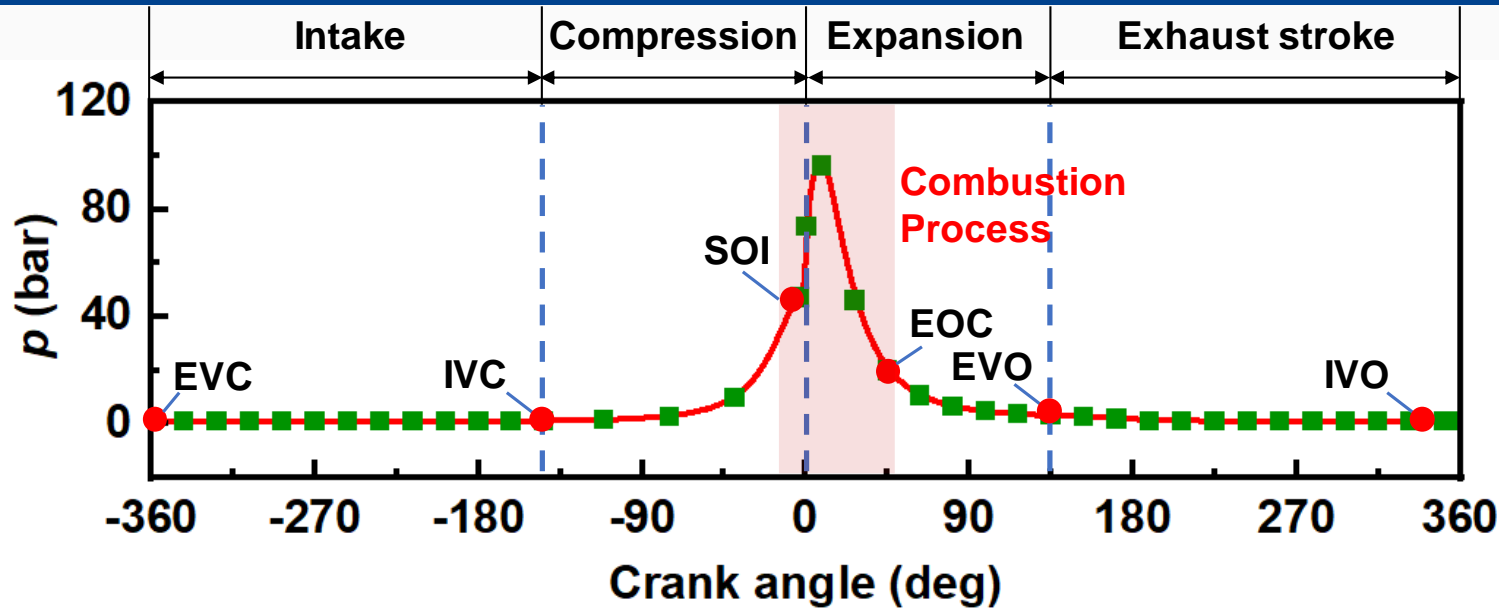
Real time

**Pressure
Temperature
Vibration**





Real-time model of in-cylinder pressure trace ²³



Discretized variable time step model

$$IMEP = \phi \frac{\eta_{th} Q_{comb}}{V_{s,real}}$$

$$\eta_{th} = 1 - \frac{1}{\epsilon_{real}^{\kappa-1}}$$

$$V_{s,real} = \frac{\epsilon_{real} - 1}{\epsilon_{real}} \frac{MRT_{IVC}}{P_{IVC}}$$

$$Q_{comb} = \frac{\eta_c H_u M_f}{1 + Y \left(\frac{1 + r_{EGR}}{1 - r_{EGR}} \right)}$$

Exhaust + valve overlap	Intake stroke	Compression stroke	Expansion stroke
$P_i = P_{em}$ $T_i = T_{em}$ $M_{residual} = \frac{P_{em} V_{TDC}}{T_{em} R}$	$P_i = P_{im} \quad T_i = \frac{P_{im} V_i}{M_i R}$ $T_{IVC} = T_{im}$ $M_{BDC} = M_{intake} + M_{residual}$ $M_{intake} = \frac{W_{ei}}{\frac{N}{2 \times 60} (1 - r_{EGR})}$ $M_i = M_{BDC} \sin^{1.5}(\theta_i / 2 \frac{\pi}{180})$	$P_i = P_{IVC} (\frac{V_{IVC}}{V_i})^{n_c}$ $T_i = T_{IVC} (\frac{V_{IVC}}{V_i})^{n_c - 1}$	$P_i = P_{EVO} (\frac{V_{EVO}}{V_i})^{n_e}$ $T_i = T_{EVO} (\frac{V_{EVO}}{V_i})^{n_e - 1}$ $P_{EVO} = P_{IVC} + \phi \frac{\kappa - 1}{\epsilon_{real}^{\kappa-1}} \frac{Q_{comb}}{V_{IVC}}$ $T_{EVO} = T_{IVC} + \phi \frac{\kappa - 1}{\epsilon_{real}^{\kappa-1}} \frac{Q_{comb}}{RM}$

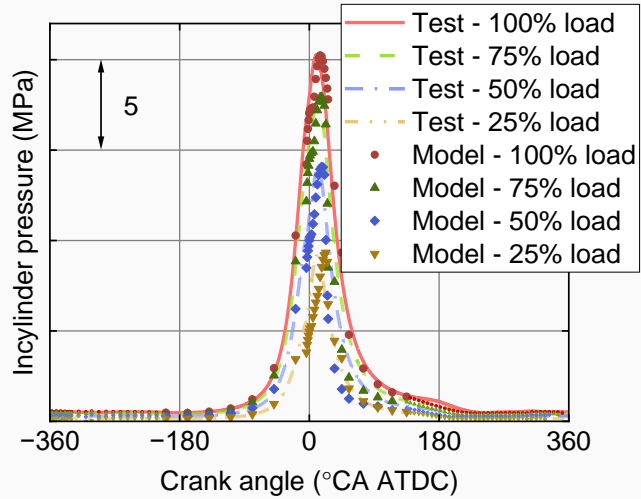


Real-time model of in-cylinder pressure trace²⁴

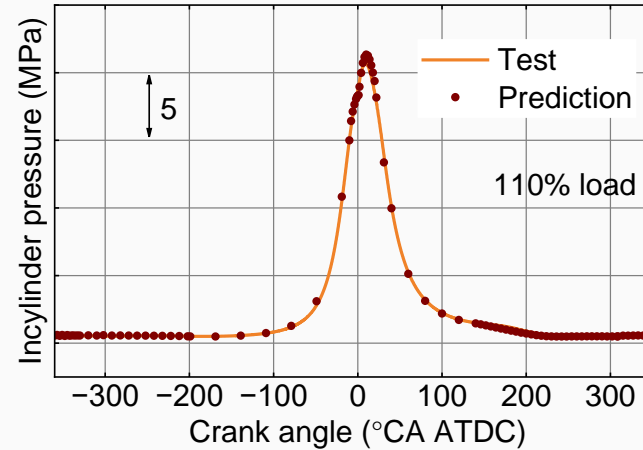


Diesel only

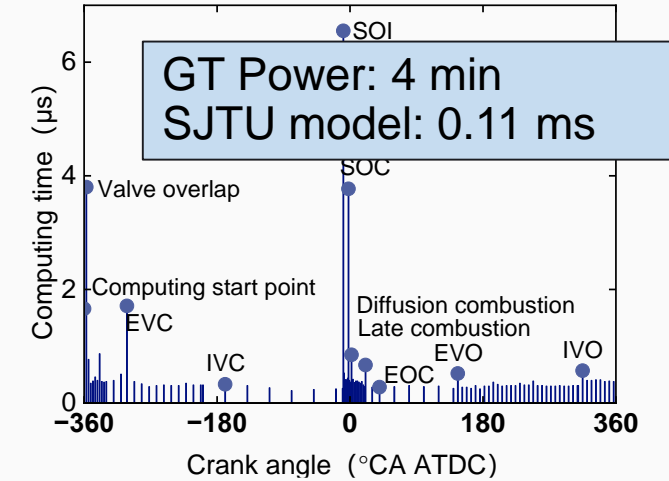
Calibration



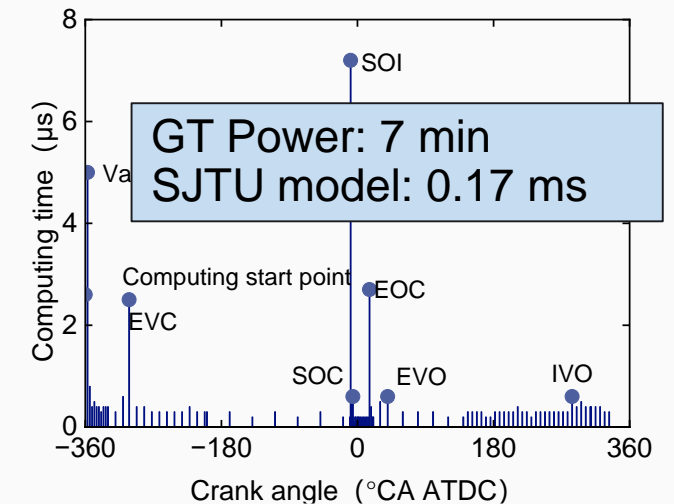
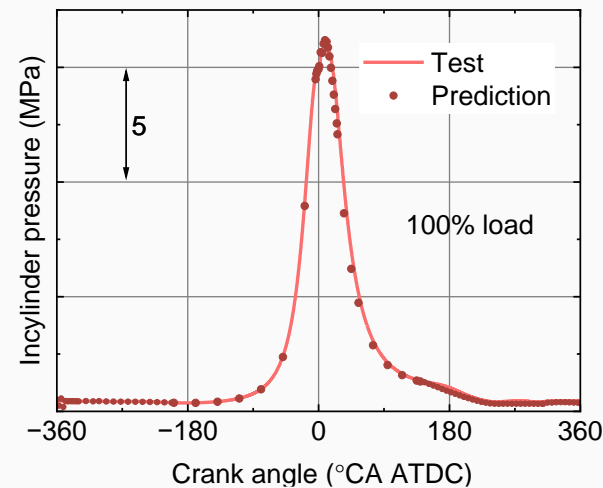
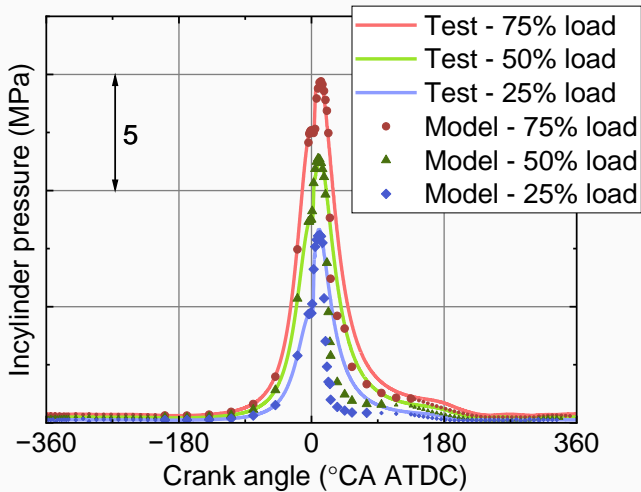
Prediction



Computing performance



Methanol/diesel
dual fuel



For a four-stroke engine run at 1000 rpm, 120 ms for one cycle, 0.16 ms for one crank angle!

Summary

- The HIL technology is imported into the digital twin to form a six-dimension digital twin framework, solving the verification issue of the digital twin modeling for complex equipment.
- The application methods of the six-dimension and the corresponding the hardware and software platforms are described in details with an example of SJTU-SCE175.

Prospective

- Intelligent operations such as fault diagnosis, risk management and predictive maintenance of marine engine systems will be further developed based on the digital twin technology.
- Digital twins for the marine engines will be further developed and applied to real ship operations, ex. the ammonia powered tugboat.





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Thank you!

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